



OOL Module

Thermal mass flow

Benefits & Characteristics

- Continuous mass flow and temperature monitoring in liquids
- Outstanding repeatability and long-term stability
- Ready to use module with digital signal outputs (I^2C)
- Suitable also for aggressive liquids with particles
- Stainless steel as single wetted material
- High accuracy between 1 and 20 kg/h

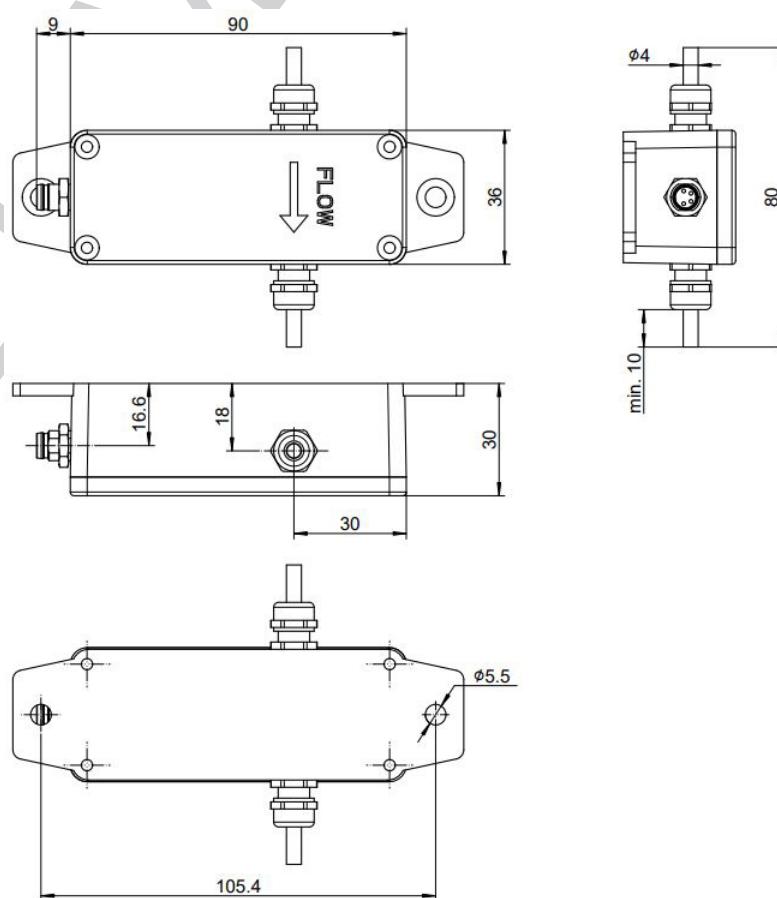
Applications

- Industrial temperature control systems
- Lubrication systems, incl. gear oil processing
- Various dosing systems, incl. food, life science, agriculture, white goods and mining
- Leakage, incl. water drip detection

Output signals

- Temperature on electronic board in $^{\circ}\text{C}$
- Temperature of liquid in $^{\circ}\text{C}$
- Power to heater in mW (non-linearized flow signal)
- Mass flow in kg/h (calibrated for H_2O , temperature compensated)

Illustration





Performance

| Parameter | Value | Unit | Comment |
|-------------------------------|------------|------------|--|
| Operating parameters | | | |
| Flow range | 0.1 ... 20 | kg/h | Calibrated for deionized water (DI-H ₂ O) |
| Temperature range | +5 ... +50 | °C | |
| Max operating pressure | 70 | bar | Estimated value |
| Warm-up time | 5 | min | |
| Flow parameters | | | |
| Accuracy | < 3 * | % f.s. | Value for DI-H ₂ O |
| Repeatability | < 0.3 | % f.s. | Value for DI-H ₂ O |
| Response time t ₆₃ | 0.5 - 1 | s | Value for DI-H ₂ O |
| Temperature sensitivity | < 0.3 | % / K f.s. | Value for DI-H ₂ O |
| Temperature parameters | | | |
| Accuracy | < 1 | °C | Value for DI-H ₂ O |
| General parameters | | | |
| Pressure loss | 0 ... 0.9 | mbar | Based on DI-H ₂ O for 1 ... 20 kg/h at 25°C |
| Orientation dependence | < 1 | % f.s. | |
| Flow insertion dependence | Yes ** | | |
| Storage temperature | 0 ... +60 | °C | |

* To achieve the specified performance, the sensor needs to be warmed up for 3 to 5 minutes to attain thermal equilibrium.

** Factory calibration is done with a straight insertion length of 30 cm, where the angle between the sensor tube and the insertion is smaller than 2°.

Mechanical parameters

| Parameter | Value | Unit | Comment |
|-----------------------|------------------------|------|-----------------------|
| Flow channel | | | |
| Media wetted material | Stainless steel 1.4301 | | |
| Length | 80.0 | mm | |
| Outer diameter | 4.0 | mm | |
| Inner diameter | 3.7 | mm | |
| Process connection | 4.0 | mm | Open ended steel tube |
| Housing | | | |
| Material | Aluminium | | |
| Width | 30 | mm | |
| Length | 90 | mm | excl. flanch |
| Height | 36 | mm | |

**General parameters**

Protection class IP65

Weight 140 g

Electrical parameters

| Parameter | Value | Unit | Comment |
|-----------------------|-----------|------|--|
| Supply voltage | 10 ... 26 | V | DC |
| Power consumption | ≤ 1 | W | |
| Electrical connection | M8 4-pin | | Connector compatible with Phoenix SACC-DSI-M8MS-4CON-L90 SH / Binder 09-3421-82-04 |

Output signal (I²C, 3.3V)

| | | |
|--------------------------------|------|-----------------------------|
| Mass flow | kg/h | Linearized, 16bit |
| Power to heater | mW | Not linearized, 16bit |
| Temperature of liquid | °C | Accuracy unspecified, 16bit |
| Temperature of microcontroller | °C | Accuracy unspecified, 16bit |

Pin Assignment

| | |
|-------|-----|
| Pin 1 | GND |
| Pin 2 | SCL |
| Pin 3 | VCC |
| Pin 4 | SDA |

Voltage supply

I²C-protocol

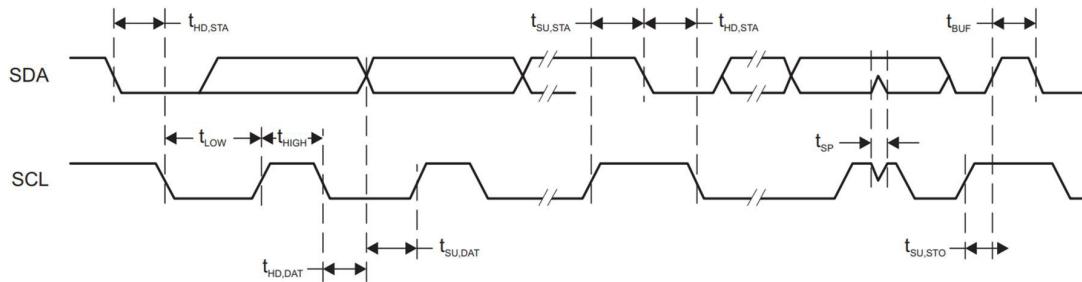
For integration with a micro-controller, the OOL module has an I²C-compatible interface which supports both 100 kHz and 400 kHz bit rates. The default I²C slave address is programmed to 0x28 and can be adjusted in the entire 7-bit address range (0x00 to 0x7F).

| Parameter | Min | Max | Unit |
|---------------|-----|-----|------|
| f_{SCL} | 100 | 400 | kHz |
| $t_{HD, STA}$ | 0.6 | | μs |
| $t_{SU, STA}$ | 0.6 | | μs |
| $t_{HD, DAT}$ | 0 | | μs |
| $t_{SU, DAT}$ | 250 | | μs |
| $t_{ST, STO}$ | 0.6 | | μs |
| | 50 | 600 | ns |

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Reading the data from OOL module

During normal operation OOL module is ready to transmit: heater power, temperature of liquid and temperature of microcontroller. Typical transmissions:

| | | | | | | | | | | | |
|-------|---------|---|-----|---------|-----|---------|-----|-----|---------|-----|------|
| Start | Address | R | ACK | Data[7] | ACK | Data[6] | ACK | ... | Data[0] | ACK | Stop |
| Start | Address | R | ACK | Data[7] | ACK | Data[6] | ACK | ... | Data[0] | ACK | Stop |

| Data | | Parameter | Unit |
|---------|-------------|--------------------------------|------|
| Data[7] | higher byte | Flow | kg/h |
| Data[6] | lower byte | | |
| Data[5] | higher byte | Heater power | mW |
| Data[4] | lower byte | | |
| Data[3] | higher byte | Temperature of liquid | °C |
| Data[2] | lower byte | | |
| Data[1] | higher byte | Temperature of microcontroller | °C |
| Data[0] | lower byte | | |

All values read from the module are in unsigned fixed-point integer Q5 format. In order to convert them to decimal format, the read value has to be divided by $2^5 = 32$. The minimum value is 0, the maximum value is 2048. The resolution of each value is $1/25 = 0.03125$.

| | | | | | | | | | | | | |
|-----|--------------|--|--|--|--|--|--|--|--|-----------------|--|-----|
| MSB | | | | | | | | | | | | LSB |
| D | Integer bits | | | | | | | | | Fractional bits | | |

Entering Command Mode

To read, write or remotely reboot the OOL module must be set to command mode by sending 0xA0.

| | | | | | | |
|-------|---------|---|-----|-------------|-----|------|
| Start | Address | W | ACK | Data = 0xA0 | ACK | Stop |
|-------|---------|---|-----|-------------|-----|------|

In the command mode OOL module switches off flow measurement and waits for further communication. If the transmission is unsuccessful, the module shall automatically reboot after 0.6 second of being idle. The module requires up to 1 ms to enter the command mode (counted from stop bit).



Entering commands

In the command mode user can transmit a 1-byte instruction to the module. The module requires up to 1 ms to process the instruction.



| | |
|-------|---|
| 0x0b: | Read Delta_T – temperature difference between heater and sensor |
| 0x0e: | Read I ² C_address – own address on I ² C bus |
| 0x2b: | Write Delta_T – temperature difference between heater and sensor |
| 0x2e: | Write I ² C_address – own address on I ² C bus, applies after reset |
| 0xa1: | Exit command mode (without reset) |
| 0xa2: | Reboot |

Reading parameters from the module

After receiving a read instruction the module fills the I²C buffer with the selected parameter. All parameters read from the module, except I²C_address, are in signed fixed-point long IQ22 format (4 bytes). To convert them to decimal format divide read value by $2^{22} = 4\ 194\ 304$. The minimum value is -512, the maximum value is 511.999 999 762. The resolution of each parameter is $1/2^{22} = 0.000\ 000\ 238$. I²C_address parameter is read in unsigned long format and internally masked with 0x3F.



| Data | | Parameter |
|---------|--------------------|-----------|
| Data[3] | 1st byte (highest) | Parameter |
| Data[2] | 2nd byte | |
| Data[1] | 3rd byte | |
| Data[0] | 4th byte (lowest) | |

After transmitting 4 bytes the module resets its internal timer and waits in command mode for the next command. The module will reboot automatically after 0.6 second if idle or unsuccessful transmission.

Writing parameters to the module

After successful write instruction the module waits for 4 bytes with the new parameter. All parameters, except I²C_address, are in signed fixed-point long IQ22 format (4 bytes). In order to convert decimal format to IQ22, the decimal value has to be multiplied by $2^{22} = 4\ 194\ 304$. To reduce the error, this calculation should be done as double precision floating point number. The minimum value is -512, the maximum value is 511.999 999 762. The resolution of each parameter is $1/2^{22} = 0.000\ 000\ 238$. I²C_address parameter is written in unsigned long format and internally masked with 0x3F. Please mind that the new I²C address applies after reboot. The module requires up to 60 ms after stop bit to flash the internal memory with the new parameter. Internal flash memory is rated for minimum 10^4 programming cycles (typically 10^5).



| Data | | Parameter |
|---------|--------------------|-----------|
| Data[3] | 1st byte (highest) | Parameter |
| Data[2] | 2nd byte | |
| Data[1] | 3rd byte | |
| Data[0] | 4th byte (lowest) | |

After receiving 4 bytes the module resets internal timer and waits in command mode for next command. The module will reboot automatically after 0.6 second of idle or unsuccessful transmission.

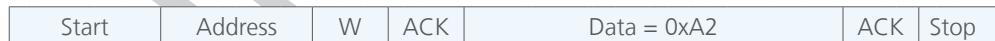
Exit command mode

After receiving this command, the module returns to normal operation, taking new parameters' values except the I²C address.



Reboot

After receiving this command, the module reboots.



Typical parameter's read sequence

To read parameter(s) from the flash memory please follow steps:

1. Write 0xA0 to the module – start the command mode
2. Wait 1 ms
3. Write 0x20...0x2f to the module – an address of the parameter
4. Wait 1 ms
5. Write 4 bytes to the module
6. Wait 60 ms
7. If needed repeat steps 3-6 for another parameter
8. Write 0xA1 to the module – exit command mode or 0xA2 – reboot the module

Recommendation for connecting the OOL Module

Based on a plastic tube with an 6.0 mm outer diameter and a 1.0 mm wall thickness:

- Ear clamps with insert ring: One-Ear clamp with insert ring 5.6-6.5



Product Photo



Order Information

| Order code | Product name |
|------------|--------------------------|
| 153331 | OOL Module V1.2.1 |
| 153332* | EvaKit OOL Module V1.2.1 |



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